

### **AMENDMENTS TO THE SPECIFICATION**

Please replace the paragraph on page 5, lines 14–16, with the following amended paragraph:

-- In the robot main body driving power cable 2a are accommodated the wire feeder driving power cable 5e, the gas valve control cable 5f, the voltage feedback cable 5g, the feeder sensor cable 3b and the welding control cable [[3a]].

Please replace the paragraph on page 5, lines 23–25, with the following amended paragraph:

-- In this way, it is not necessary to separately connect a welding control cable [[3a]] and the wire feeder sensor cable 3b required for welding. This reduces the installation work man-hours on site.

Please replace the paragraph starting on page 5, line 32, with the following amended paragraph:

-- In this way, it is possible to reduce the installation work man-hours on site and overall cost without separately extending the welding control cable [[3a]] and the wire feeder sensor cable 3b required for welding.